Please amend the claims as follows:

1. (Currently Amended) A slip control device of a four-wheel-drive vehicle to prevent any slip of wheels by varying the torque transmission distribution to a front wheel side and a rear wheel side via a transfer clutch, and controlling the coupling force of said transfer clutch when the wheels slip, said device comprising:

means for calculating an indicated value to the coupling force of said transfer clutch in a first area in which the <u>a</u> wheel slip quantity is not exceeding a preset value;

means for correcting the indicated value to the coupling force of said transfer clutch in said first area by a correction value according to a tight cornering brake quantity; and

means for calculating the indicated value to the coupling force of said transfer clutch when transferring to a second area in which the wheel slip quantity exceeds the preset value from said first area as a value of the indicated value in said first area added to the indicated value according to the slip quantity in said second area.

- 2. (Original)The slip control device of a four-wheel-drive vehicle according to Claim 1, wherein said correction value is calculated based on the vehicle speed.
- 3. (Original) The slip control device of a four-wheel-drive vehicle according to Claim 1, wherein said correction value is calculated based on the vehicle speed and the wheel speed ratio.

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4. (Original) The slip control device of a four-wheel-drive vehicle according to Claim 1, wherein said correction value is calculated based on the vehicle speed and the throttle position of an engine.

- 5. (Original) The slip control device of a four-wheel-drive vehicle according to Claim 1, wherein said correction value is calculated based on the vehicle speed and the steering angle.
- 6. (Original) The slip control device of a four-wheel-drive vehicle according to Claim 1, wherein said correction value is calculated based on the lateral acceleration and the wheel speed ratio.
- 7. (Original) The slip control device of a four-wheel-drive vehicle according to Claim 1, wherein said correction value is calculated based on the lateral acceleration and the steering angle.
- 8. (Original) The slip control device of a four-wheel-drive vehicle according to Claim 1, wherein said correction value is calculated based on the yaw rate and the wheel speed ratio.
- 9. (Original) The slip control device of a four-wheel-drive vehicle according to Claim 1, wherein said correction value is calculated based on the yaw rate and the steering angle.

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10. (New) A method of controlling slip in a vehicle, comprising:

calculating a transfer clutch value in a first area in which a wheel slip quantity is not exceeding a preset value;

correcting the transfer clutch value in said first area by a correction value; and calculating the transfer clutch value when transferring to a second area in which the wheel slip quantity exceeds the preset value from said first area as a value of the transfer clutch value in said first area added to a transfer clutch value according to the slip quantity in said second area.

11. (New) A slip control device, comprising:

means for calculating a transfer clutch value in a first area in which a wheel slip quantity is not exceeding a preset value;

means for correcting the transfer clutch value in said first area by a correction value; and

means for calculating the transfer clutch value when transferring to a second area in which the wheel slip quantity exceeds the preset value from said first area as a value of the transfer clutch value in said first area added to a transfer clutch value according to the slip quantity in said second area.